

Compositional analyses of dynamical systems

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Outline

1 Introduction

- Composition, as a general phenomenon
- Plan of the talk

2 Compositional mappings

3 The Pixel Array approach to solving nonlinear systems

4 Co-design and applications

5 Conclusion

E pluribus unum

Composition

Composition is **assembling** many **things** together to make one **thing**.¹

¹Color scheme and category-theoretic formalism:
“**thing**” = *object*, “**arrangement**” = *morphism*, “**nesting**” = *composition*.

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Composition is **assembling** many **things** together to make one **thing**.¹

- One says that Y is composed of **pieces** $X_1, \dots, X_n$.
 - We should specify not only the **pieces**, but also their **arrangement**.
 - We could denote an **arrangement** $\varphi: X_1, \dots, X_n \rightarrow Y$.
 - Arrangements can be **nested** inside each other.

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 - We could denote an **arrangement** $\varphi: X_1, \dots, X_n \rightarrow Y$.
 - Arrangements can be **nested** inside each other.
- This leads naturally to the notion of operad $\mathcal{O}$, which specifies:
 - the set of possible **things** $X, Y, \dots$;
 - the set of **arrangements** φ, ψ by which things can be composed;
 - how **nesting** works $\psi \circ (\varphi_1, \dots, \varphi_n)$.

Let's give two very different examples, to see the scope.

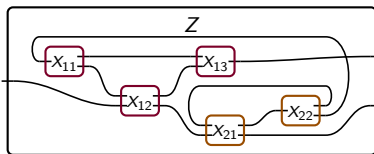
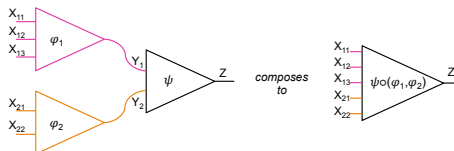
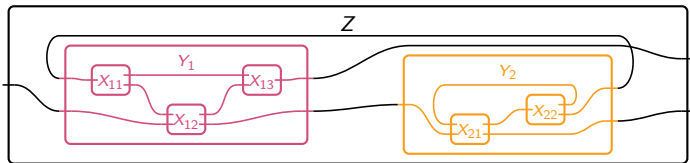
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Arrangements 1: wiring diagrams

There is an operad $\mathcal{D}$ for composing hierarchical dynamical systems.

- Note the **things**, **arrangements**, and **nesting** here.



Arrangements 2: hierarchical protein materials

There is an operad $\mathcal{M}$ for composing hierarchical protein materials.

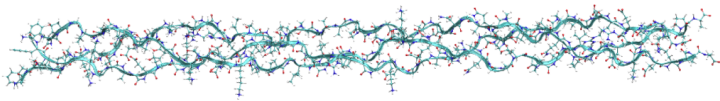
- A **protein** is an **arrangement** of simpler **proteins**.
 - There are “atomic” proteins, namely amino acids.
 - Protein materials include your skin: stretchable, breathable, waterproof.²

²Giesa, T.; Jagadeesan, R.; Spivak, D.I.; Buehler, M.J. (2015) “Matriarch: a Python library for materials architecture.” *ACS Biomaterials Science & Engineering*.

Arrangements 2: hierarchical protein materials

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- A **protein** is an **arrangement** of simpler **proteins**.
 - There are “atomic” proteins, namely amino acids.
 - Protein materials include your skin: stretchable, breathable, waterproof.²
- A new protein can be assembled from a finite set of proteins
 - arranged in series or parallel, or
 - arranged in helices, double helices, any conceivable curve, etc.



- (Computer MD versions of) proteins model this operad.

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Plan: compositional analyses of dynamic systems

So composition—one thing out of many—can be formalized by operads.

- There's also a mathematical definition of *compositional analysis*.
 - It's something we can compute, but which also composes well:
 - Component-level analyses can be combined to provide a system-level analysis.

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- Why? Compositional analysis is future-proof analysis.
 - Example: *Average* is not compositional; *sum* and *count* are.
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 - Example: *Average* is not compositional; *sum* and *count* are.
 - Always expect your machine to be used in a larger system.
- I will give several examples of compositional mappings and analyses.
 - Discretization of dynamical systems is compositional.
 - Steady state analyses are compositional.
- I'll also explain a few other compositional frameworks.
 - A new way of solving systems of non-linear equations.
 - A mathematical theory of collaborative design.

Outline

1 Introduction

2 **Compositional mappings**

- Operads and algebras
- Compositional mappings
- Euler, Runge Kutta
- Steady states

3 The Pixel Array approach to solving nonlinear systems

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E pluribus unum

Operads and algebras: the syntax and semantics of composition

There is a category-theoretic object, called an **operad**.³

- Operads are a framework for composing systems of systems.
- Operads are a sort of **syntax**; their **semantics** are called **algebras**.
- Or think operad=**interface logic**; algebra=**inhabitants**.
- Some examples of compositional structures that operads can model:
 - Every **recipe**—a sequence of smaller recipes—is an operad.
(**Performance plans might constitute an algebra for it.**)

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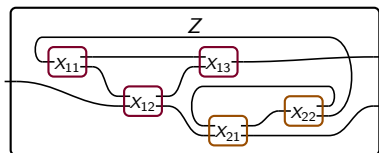
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 - Every **context-free grammar** is an operad.
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 - Every sort of wiring diagram, as in electric circuits or signal flow.
(We'll discuss several different algebras for wiring diagrams.)
- I'll describe operads of wiring diagrams next.

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Multiple interpretations for the same operad

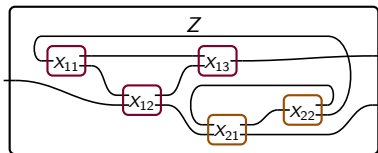
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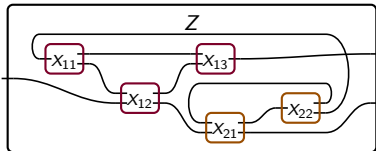


But there are many different **semantics** for this operad.

- Continuous dynamical systems compose according to these pictures.
- Discrete dynamical do too. Hybrid systems do too.

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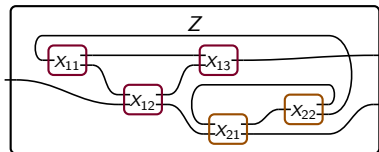
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- Continuous dynamical systems compose according to these pictures.
- Discrete dynamical do too. Hybrid systems do too.
- Mathematicians recognized long ago that matrices (tensors) do too.
 - Sequential composition is “matrix multiplication”.
 - Parallel composition is “Kronecker product”.
 - Feedback is the block-trace operator.

Each of these semantics interpretations is formalized as an **algebra**.

Compositional mappings: translating between algebras

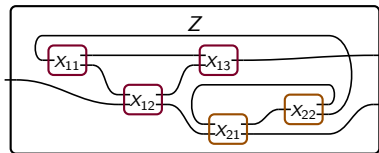
Suppose A and B are both **algebras** for the same **operad** $\mathcal{O}$.



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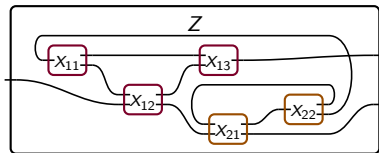


- For example, A =continuous dynamics, B =discrete dynamics.
- A comp'l mapping (algebra morphism) $A \rightarrow B$ does the following:
 - For each box, it translates each A -inhabitant to a B -inhabitant.
 - For each wiring diagram, it satisfies an equation:

translate-then-compose = compose-then-translate.

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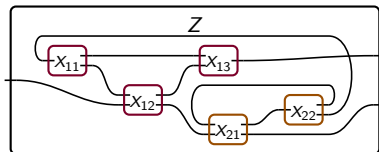
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$$\text{translate-then-compose} = \text{compose-then-translate}.$$

Question: is “discretizing a continuous dynamical system” compositional?

Discretization is compositional

Rephrasing the question, suppose there is a continuous DS in each box:



You have the following choices; what's the difference between them?

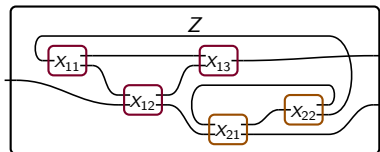
- Choice 1: compose the continuous systems and discretize the result;
- Choice 2: discretize each and then compose the discrete systems.

⁴Spivak "The steady states of dynamical systems". *arXiv* 1512.00802.

⁵Ngotiaoco "Compositionality of the Runge-Kutta Method". *arXiv* 1707.02804.

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- Choice 1: compose the continuous systems and discretize the result;
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“Discretization is compositional”: you get the same result either way.

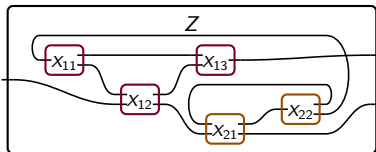
- This requires proof: arbitrary wiring diagrams, arbitrary DS's.
- I proved it for Euler;⁴ my student proved it for Runge Kutta.⁵

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Bifurcation diagrams are compositional

Suppose there's a DS (cont/disc/hybrid) in each box.

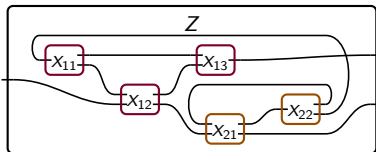


To each box, associate the “bifurcation diagram” of the DS.

- It's the n -dimensional plot of inputs/outputs that have a steady state.
- Pixelate it to form an n -dimensional tensor.
- We said that n -dim'l tensors are a semantics for wiring diagrams.

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“Bifurcation diagrams are compositional”: get the same answer whether

- you first compose the DS's and then plot the bifurcation diagram; or
- you first plot the bifurcation diagrams, then compose these tensors.

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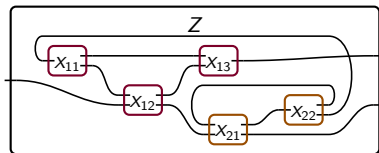
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- 2 Compositional mappings
- 3 The Pixel Array approach to solving nonlinear systems**
 - Solving systems of equations is compositional
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E pluribus unum

From steady states to systems of equations

Steady states of a DS are solutions to a system of equations, $\dot{\mathbf{x}} = 0$.

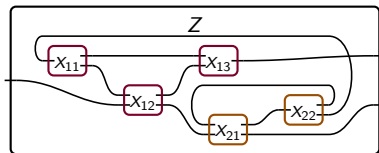
- For interconnected systems, the various systems are combined.



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- For interconnected systems, the various systems are combined.



- Some variables are shared (as dictated by the wiring diagram).
- So what did “bifurcation diagrams are compositional” stuff tell us?
 - In fact, that was about plotting equations (as dots on a screen).
 - I said that to find steady states, multiply the plots as matrices.
 - Turns out this is really about solving systems of equations.
- So we’re solving systems of *non-linear* equations by matrix arithmetic.

Imagining the pixel array method

Separately plot the solutions to equations: $f(x, w) = 0$ and $g(w, y) = 0$.

- Plot each in its own bounding box, say in the range $[-1.5, 1.5]$.
- Consider the plots as matrices M, N whose entries are on/off pixels.
- That is, M and N are *boolean matrices* corresponding to f and g .

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Multiplying these two matrices MN yields...

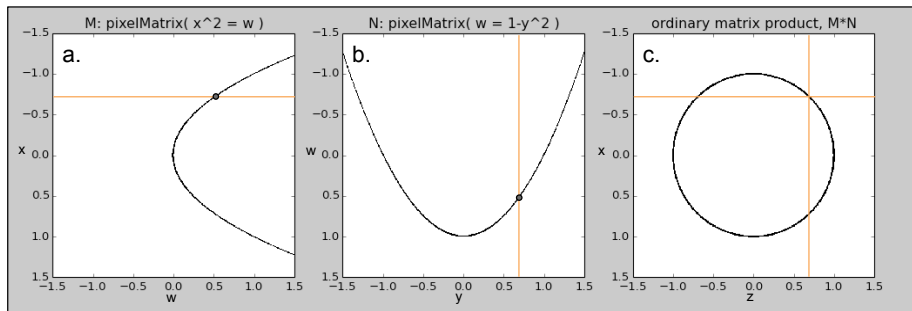
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Multiplying these two matrices MN yields the simultaneous solution.

- For example, plot equations $x^2 = w$ and $w = 1 - y^2$, and multiply.



A more complex example

The following eq's are not differentiable, nor even defined everywhere.

$$\cos(\ln(z^2 + 10^{-3}x)) - x + 10^{-5}z^{-1} = 0 \quad (\text{Equation 1})$$

$$\cosh(w + 10^{-3}y) + y + 10^{-4}w = 2 \quad (\text{Equation 2})$$

$$\tan(x + y)(x - 2)^{-1}(x + 3)^{-1}y^{-2} = 1 \quad (\text{Equation 3})$$

Q: For what values of w and z does a simultaneous solution exist? ⁶

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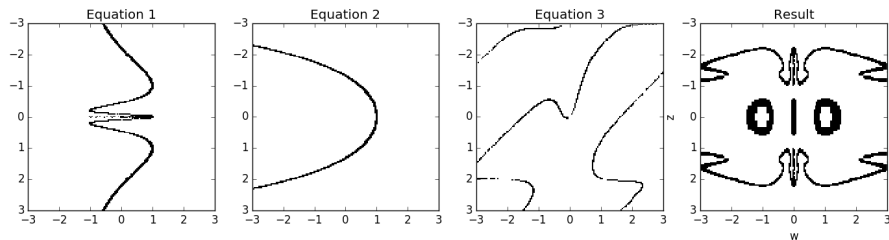
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 - Mathematical co-design
 - Possible applications to reachability
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Mathematical co-design

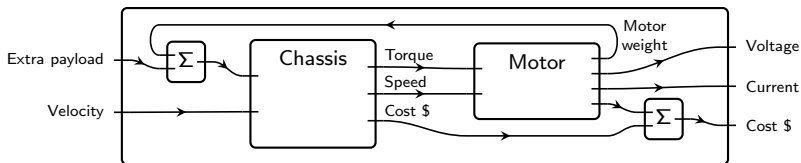
Designing complex systems of systems is collaborative.

- Many teams working on the same project: independent or dependent?
 - Each team's internal decisions have impact on other teams.
 - Feedback loops are prevalent in design.

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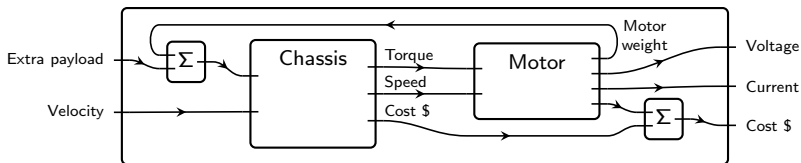
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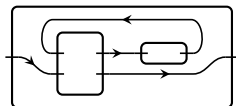


- There is a compositional theory of co-design (due to Andrea Censi).
 - Each box is a design problem.
 - Inside may be another interconnected system of design problems.

The underlying math of co-design

What is a design problem in the underlying math? $P \vdash \Phi \vdash R$

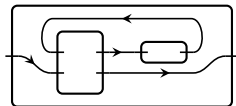
- Design is about feasibility: resources provided vs. resources required.
- Each resource (wire) is modeled as a poset, the order is by preference.
- Feasibility is a monotonic function $\Phi: P^{\text{op}} \times R \rightarrow \{\mathbb{F}, \mathbb{T}\}$.



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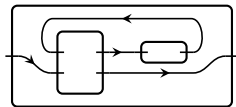
Potential application to reachability analysis for interconnected DS's.

- Imagine an initialized DS in each box. $\mathbb{R}^m \vdash \boxed{\Phi} \vdash \mathbb{R}^n$
- To each wire, associate a poset of open sets U in the manifold.

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- To each wire, associate a poset of open sets U in the manifold.
- To a box, need $\Phi(U_1, U_2) \in \{\text{F}, \text{T}\}$ for each $U_1 \subseteq \mathbb{R}^m$ and $U_2 \subseteq \mathbb{R}^n$.
- Put $\Phi(U_1, U_2) = \text{T}$ iff, by keeping input in U_1 , output is kept in U_2 .

Combining these in a system, we get the overall reachability relation.

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 - Operads: out of many, one

E pluribus unum

Summary

Operad: a mathematical framework defining a given sort of composition.

- What are your interfaces? What sorts of arrangements are allowed?
- We saw a few operads: mostly wiring diagrams.
- We also briefly touched on operads for proteins, recipes, grammars.

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Algebra: the set of inhabitants for interfaces, and the combination rules.

- Focused on dynamical systems; briefly also tensors and co-design.
- Compositional mappings and analyses (discretization, bifurcation).
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- Mentioned co-design theory, and possible application to reachability.

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Operads offer a flexible framework for discussing compositionality.

Questions and comments welcome!