

Lenses: applications and generalizations

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Outline

1 Introduction

- An agent in an environment
- Lenses organize interactions
- Lenses in CT

2 Some applications of lenses

3 Generalizing lens categories

4 Conclusion

An agent in an environment

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- It means agent and environment are communicating somehow.
 - The agent *observes* the environment and *acts* on it.

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- The agent has an effect on the environment and vice versa.
- What does that mean?
- It means agent and environment are communicating somehow.
 - The agent *observes* the environment and *acts* on it.
 - The agent's state affects that of the environment and vice versa.
 - Agent affects environment through *action*.
 - Environment affects agent through *observation*.
 - Each is affected in that it undergoes a change of *state*.

How shall we model this mathematically?

A formalization of agent/environment interaction

Setup:

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- a set S_{Ag} for the possible states of the agent,
- a set S_{En} for the possible states of the environment,
- a set A for the possible actions, and
- a set O for the possible observations.

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- Environment's state is updated by the action via $S_{En} \times A \rightarrow S_{En}$.

How to organize all this stuff?

We have sets S_{Ag} , S_{En} , A , O and functions

$$\begin{array}{ll} S_{Ag} \rightarrow A & S_{En} \rightarrow O \\ S_{Ag} \times O \rightarrow S_{Ag} & S_{En} \times A \rightarrow S_{En} \end{array}$$

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How to organize all this stuff?

- Each pair of functions is a special case of what are called *lenses*.
- Lenses are the morphisms in a cat **Lens**, whose objects are pairs $\begin{pmatrix} X \\ Y \end{pmatrix}$.
 - The lenses from our agent/environment setup would be denoted:
 - $\begin{pmatrix} S_{Ag} \\ S_{Ag} \end{pmatrix} \rightarrow \begin{pmatrix} A \\ O \end{pmatrix}$ and $\begin{pmatrix} S_{En} \\ S_{En} \end{pmatrix} \rightarrow \begin{pmatrix} O \\ A \end{pmatrix}$

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Lenses have been coming up in the ACT community a lot lately.

Applications of lenses

There have been many uses of lens-like things over the years.

- Bidirectional transformations (Oles),
- dialectica categories and linear logic (de Paiva),
- the view-update problem in databases (Hoffman, Pierce),
- functional programming (Gibbons, Oliveira, Palmer, Kmett),
- wiring diagrams, discrete and continuous dynamical systems (Spivak),
- open economic games (Ghani, Hedges),
- supervised learning (Fong, Spivak, Tuyéras).

I'll explain a few of these as we go.

Bringing lenses into the fold

The formula lenses and their composition is kinda weird:

$$\mathbf{Lens} \left(\left(\begin{array}{c} A \\ A' \end{array} \right), \left(\begin{array}{c} B \\ B' \end{array} \right) \right) := \left\{ (f, f^\sharp) \mid \begin{array}{l} f: A \rightarrow B \\ f^\sharp: A \times B' \rightarrow A' \end{array} \right\}.$$

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- Today: we'll first see **Lens** as part of a larger category that
 - provides a geometrical perspective,
 - is more familiar to category theorists, and
 - has better formal properties.

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- Today: we'll first see **Lens** as part of a larger category that
 - provides a geometrical perspective,
 - is more familiar to category theorists, and
 - has better formal properties.
- We then generalize further to pick up some close cousins of lenses.

Other generalizations

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- Kmett, Riley, etc. have generalized lenses to *optics*.
 - Briefly: for any monoidal category $(\mathcal{C}, I, \otimes)$, ...
 - an optic $\binom{A}{A'} \rightarrow \binom{B}{B'}$ can be identified with an element of

$$\int^{M \in \mathcal{C}} C(A, M \otimes B) \times C(M \otimes B', A').$$

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- This can be generalized even further using Tambara modules.
- However, it's not the direction I want to go today.

Plan of the talk

Plan for the rest of the talk:

- Some applications of lenses
- Generalizing lens categories

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Agent in an environment

We began with an agent in an environment.

$$\begin{aligned} S_{\text{Ag}} &\rightarrow A \\ S_{\text{Ag}} \times O &\rightarrow S_{\text{Ag}} \end{aligned}$$

$$\begin{aligned} S_{\text{En}} &\rightarrow O \\ S_{\text{En}} \times A &\rightarrow S_{\text{En}} \end{aligned}$$

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These are lenses $\begin{pmatrix} S_{\text{Ag}} \\ S_{\text{Ag}} \end{pmatrix} \rightarrow \begin{pmatrix} A \\ O \end{pmatrix}$ and $\begin{pmatrix} S_{\text{En}} \\ S_{\text{En}} \end{pmatrix} \rightarrow \begin{pmatrix} O \\ A \end{pmatrix}$. What's up with the flip?

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- Idea: if we multiply these lenses we get:

$$\left(\begin{smallmatrix} S_{\text{Ag}} \times S_{\text{En}} \\ S_{\text{Ag}} \times S_{\text{En}} \end{smallmatrix} \right) \rightarrow \left(\begin{smallmatrix} A \times O \\ O \times A \end{smallmatrix} \right)$$

and there's an “symmetry” lens morphism $\left(\begin{smallmatrix} A \times O \\ O \times A \end{smallmatrix} \right) \rightarrow \left(\begin{smallmatrix} 1 \\ 1 \end{smallmatrix} \right)$.

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- Composing, we get a single lens $\begin{pmatrix} S \\ S \end{pmatrix} \rightarrow \begin{pmatrix} 1 \\ 1 \end{pmatrix}$, where $S = S_{\text{Ag}} \times S_{\text{En}}$.

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We can see this as part of a bigger picture.

The agent-environment system

So what were we doing when we:

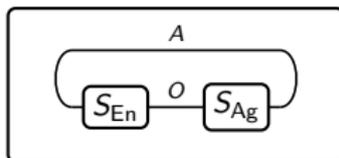
- started with lenses $\begin{pmatrix} S \\ S \end{pmatrix} \rightarrow \begin{pmatrix} A \\ O \end{pmatrix}$ and $\begin{pmatrix} S' \\ S' \end{pmatrix} \rightarrow \begin{pmatrix} O \\ A \end{pmatrix}$,
- multiplied them together to get a map $\begin{pmatrix} S \times S' \\ S \times S' \end{pmatrix} \rightarrow \begin{pmatrix} A \times O \\ O \times A \end{pmatrix}$, and then
- composed the result with a canonical map to $\begin{pmatrix} 1 \\ 1 \end{pmatrix}$?

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It turns out we were doing this:

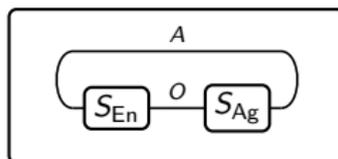


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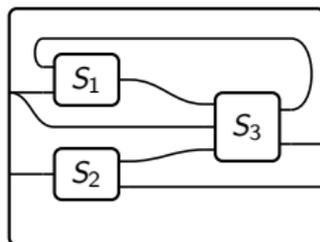
So what were we doing when we:

- started with lenses $(S) \rightarrow (O)$ and $(S') \rightarrow (O)$,
- multiplied them together to get a map $(S \times S') \rightarrow (O \times A)$, and then
- composed the result with a canonical map to $(\frac{1}{1})$?

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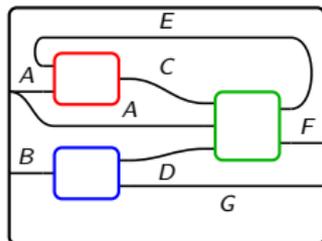


More generally we can consider open systems with many interacting agents



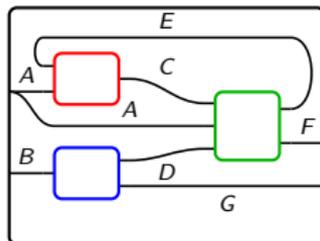
Wiring diagrams

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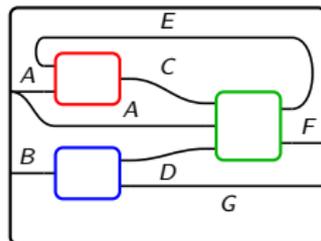
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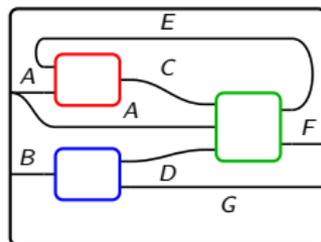


For each box, we have a pair $\begin{pmatrix} \text{outputs} \\ \text{inputs} \end{pmatrix}$.

- We have three interior boxes: $\begin{pmatrix} C \\ E \times A \end{pmatrix}$, $\begin{pmatrix} D \times G \\ B \end{pmatrix}$, $\begin{pmatrix} E \times F \\ C \times A \times D \end{pmatrix}$.
- We have one exterior box: $\begin{pmatrix} F \times G \\ A \times B \end{pmatrix}$.

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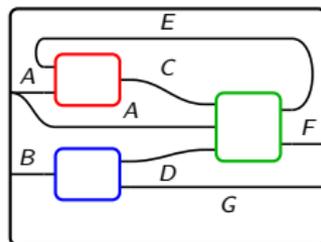


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- We have one exterior box: $\left(\begin{smallmatrix} F \times G \\ A \times B \end{smallmatrix} \right)$.
- The wiring diagram induces a lens $\left(\begin{smallmatrix} C \times D \times G \times E \times F \\ E \times A \times B \times C \times A \times D \end{smallmatrix} \right) \rightarrow \left(\begin{smallmatrix} F \times G \\ A \times B \end{smallmatrix} \right)$

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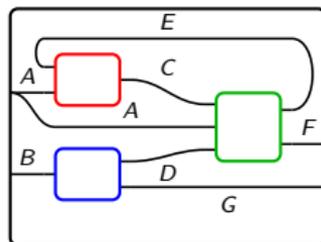
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- Both maps are just projections and diagonals:

$$C \times D \times G \times E \times F \rightarrow F \times G$$

$$C \times D \times G \times E \times F \times A \times B \rightarrow E \times A \times B \times C \times A \times D$$

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Every wiring diagram gives a lens made of projections and diagonals.

WDs and discrete dynamical systems

A discrete dynamical system of type $\binom{A}{A'}$ consists of

- A set S
- A function $f^{\text{rdt}}: S \rightarrow A$ called “readout”
- A function $f^{\text{upd}}: S \times A' \rightarrow S$ called “update”
- Optional: an element $s_0 \in S$ called “initial state”.

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This is just a lens $\begin{pmatrix} f^{\text{rdt}} \\ f^{\text{upd}} \end{pmatrix}: \begin{pmatrix} S \\ S \end{pmatrix} \rightarrow \begin{pmatrix} A \\ A' \end{pmatrix}$, with optional $\begin{pmatrix} s_0 \\ ! \end{pmatrix}: \begin{pmatrix} 1 \\ 1 \end{pmatrix} \rightarrow \begin{pmatrix} S \\ S \end{pmatrix}$.

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- We'll denote this setup by writing S , or (S, s_0) inside the box

$$A' \text{ --- } \boxed{S} \text{ --- } A \quad \text{or} \quad A' \text{ --- } \boxed{S, s_0} \text{ --- } A$$

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- A wiring diagram is a lens $\binom{A_1}{A'_1} \otimes \cdots \otimes \binom{A_n}{A'_n} \rightarrow \binom{B}{B'}$, and
- Each dynamical system is a lens $\binom{S_i}{S_i} \rightarrow \binom{A_i}{A'_i}$. So composing...
- We get a dynamical system $\binom{S_1 \times \cdots \times S_n}{S_1 \times \cdots \times S_n} \rightarrow \binom{B}{B'}$ in outer box.

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This story of DS's and WD's existed years before I knew about lenses.

Learners

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 - It also has an update-backprop function $P \times A' \times A \rightarrow P \times A'$.

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Our category **Learn** is just **Para**(**Lens**).

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Can we do better?

Continuous dynamical systems?

Recall that a discrete dynamical system with inputs A' and outputs A is:

- A set S
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 The two notions are quite similar, but can we see the latter as a lens?

Outline

- 1 Introduction
- 2 Some applications of lenses
- 3 Generalizing lens categories**
- 4 Conclusion

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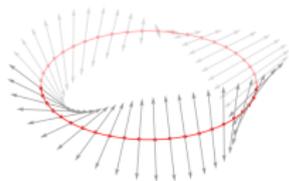
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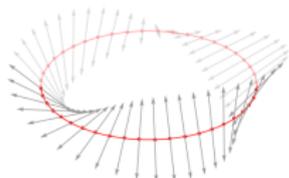
Suggestion: think of objects as “bundles.”

What are bundles?



The term bundle is most used in algebraic topology and geometry.

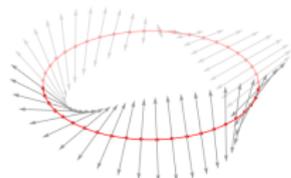
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- A *bundle* is a special kind of morphism $p: E \rightarrow B$ in a category.
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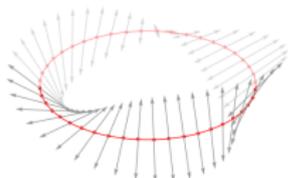
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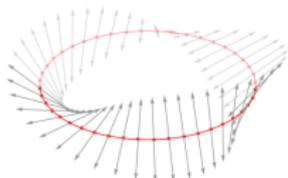
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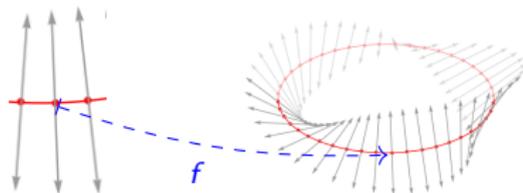
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The fiber over any $b_1 \in B_1$ is the same as that over its image $f(b_1)$.



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The usual sort of bundle morphism is just a commutative square

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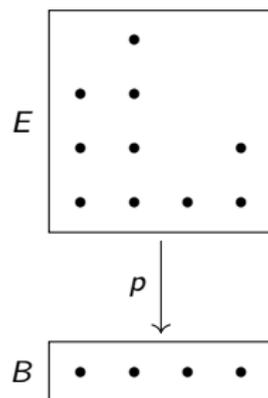
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There's a strong relationship between the AG-style maps and lenses.

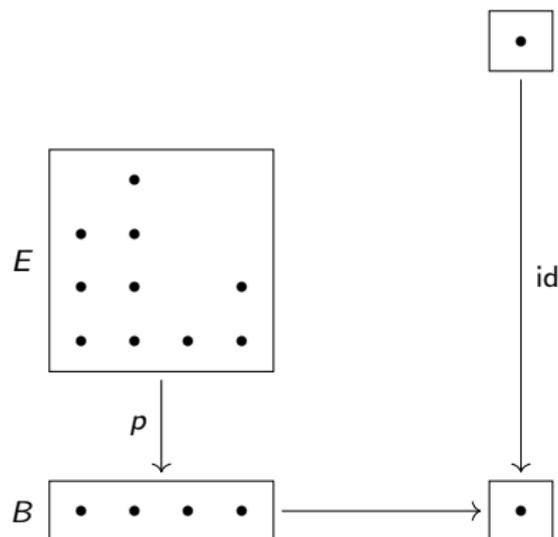
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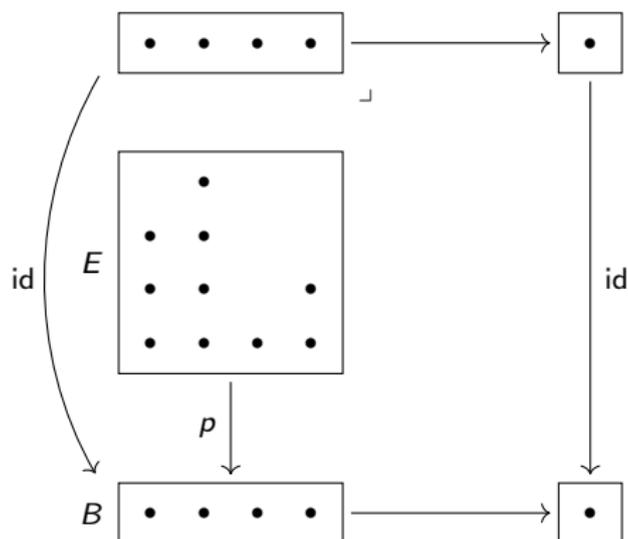
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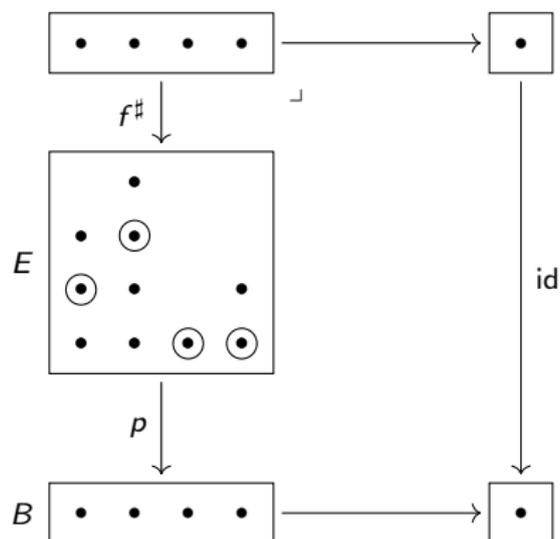
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Interpretation of bimorphic lenses as trivial bundles

We will see that **Lens** sits inside this category of bundles.

- That is, there is a fully faithful functor **Lens** \rightarrow **Bund**.
- Send lens object $\begin{pmatrix} B \\ B' \end{pmatrix}$ to the trivial bundle (projection) $B \times B' \rightarrow B$.
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Such a map $f^\sharp : B_1 \times B'_2 \rightarrow B_1 \times B'_1$, — in order to commute with π_1 — has no choice on the B_1 factor. Thus it can be identified with a map $f^\sharp : B_1 \times B'_2 \rightarrow B'_1$.

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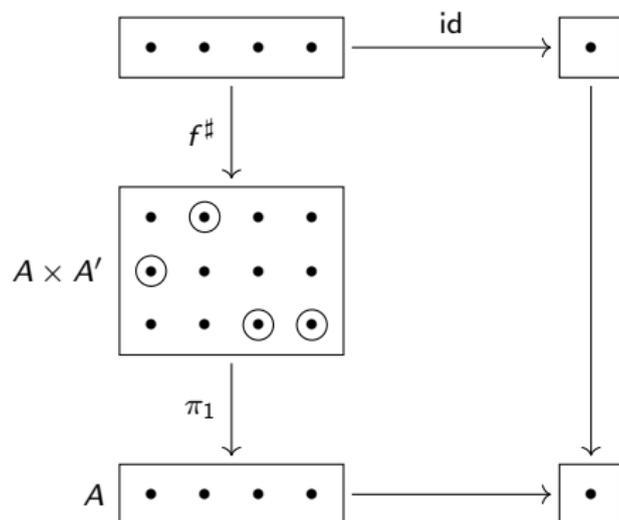
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Let's change the name **Bund** to **Lens'**.

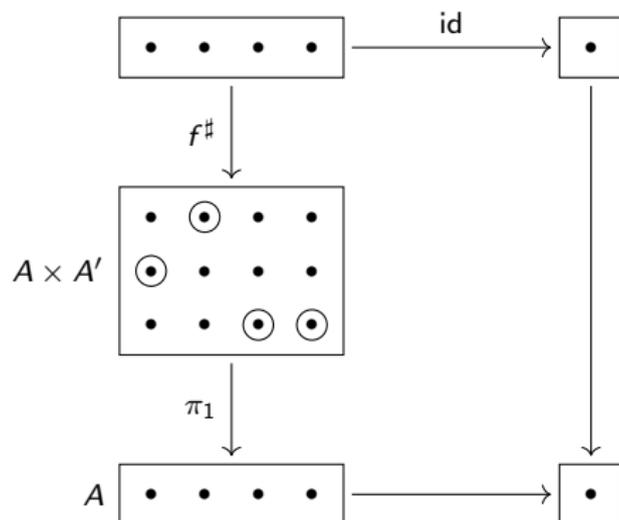
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This can be identified with a map $f^\# : A \rightarrow A'$.

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This suggests the following way of thinking of (generalized) lenses.

- An object $\binom{A}{A'}$ consists of contexts and actions
 - A is the contexts; in each $a : A$ there are $A'(a)$ actions available.

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 - Example $\binom{S}{TS}$. At each $s : S$, which tangent direction to go in?
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 - Special case $A = A' = 1$, a discrete dynamical system!

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We denote by $\binom{B}{E}$ the bundle whose

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Note that $\binom{B}{B'}$ really means the trivial bundle $B \times B' \rightarrow B$.

- I've recently been denoting $\binom{B}{E}$ by $\left[\begin{array}{c} E \\ B \end{array} \right]$.
- So we have $\left[\begin{array}{c} TS \\ S \end{array} \right]$. Looks more bundley.
- If we want, we could reserve $\binom{A}{A'}$ for usual lenses (trivial bundles).

Ringed spaces

In algebraic geometry they study *ringed spaces* (X, \mathcal{O}_X) .

- Here X is a topological space and \mathcal{O}_X is a sheaf of rings on it.
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A morphism of ringed spaces $(f, f^\#): (X, \mathcal{O}_X) \rightarrow (Y, \mathcal{O}_Y)$ is:

- A continuous map $f: X \rightarrow Y$
- A map of sheaves $f^*\mathcal{O}_Y \rightarrow \mathcal{O}_X$.
- That is, it's a map $\begin{bmatrix} \mathcal{O}_X \\ X \end{bmatrix} \rightarrow \begin{bmatrix} \mathcal{O}_Y \\ Y \end{bmatrix}$.

Continuous dynamical systems

Recall: if A', A are manifolds, a *continuous dynamical system* is:

- A manifold S , (tangent bundle TS),
- A differentiable map $f^{\text{rdt}}: S \rightarrow A$,
- A differentiable map $f^{\text{dyn}}: S \times A' \rightarrow TS$

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But from the bundle perspective that commutative diagram is baked in.

$$\begin{array}{ccc}
 A' \times S & \longrightarrow & A \times A' \\
 f^\# \downarrow & \lrcorner & \downarrow \pi_1 \\
 TS & & \\
 \pi \downarrow & & \downarrow \\
 S & \xrightarrow{f} & A
 \end{array}$$

In other words the dynamical system is just a lens map $\left[\begin{smallmatrix} TS \\ S \end{smallmatrix} \right] \rightarrow \left[\begin{smallmatrix} A' \\ A \end{smallmatrix} \right]$

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 - If we insert or deduplicate it, i.e. have $Q_*I_1 \rightarrow I_2\dots$
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 \sum_{I_1: B_1\text{-Inst}} Q_* I_1 / B_2\text{-Inst} & \longrightarrow & \sum_{I_2: B_2\text{-Inst}} I_2 / B_2\text{-Inst} \\
 \downarrow \text{pushout as above} & \lrcorner & \downarrow \pi_1 \\
 \sum_{I_1: B_1\text{-Inst}} I_1 / B_1\text{-Inst} & & \\
 \downarrow \pi_1 & & \\
 B_1\text{-Inst} & \xrightarrow{Q_*} & B_2\text{-Inst}
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- Then define $\mathbf{Lens}_{\mathcal{E}}$ as a variant of the Grothendieck construction.
- The following are equivalent:
 - The opposite of the covariant Grothendieck construction for \mathcal{E} .
 - The contravariant Grothendieck for the pointwise opposite of \mathcal{E} .
 - The category with
 - objects $\{(B, E) \mid B \in \mathcal{B}, E \in \mathcal{E}(B)\}$
 - morphisms $(B_1, E_1) \rightarrow (B_2, E_2)$ given by “lensy” $(f, f^\#)$.

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- Take $\mathcal{B} := \{\text{comonoids } (c, \epsilon, \delta) \text{ in } \mathcal{M}\}$
- Take $\mathcal{E}(c) := \mathbf{coKl}(c \otimes -)$, the coKleisli cat. of comonad $x \mapsto c \otimes x$.
- In $\begin{bmatrix} m \\ c \end{bmatrix}$, think of m as the product coalgebra $c \otimes m$, “trivial bundle”.

The right generalization of Lens?

We've seen many different lens-like categories \mathcal{L} .

- For each, there's a category \mathcal{B} and a functor $\mathcal{E}: \mathcal{B}^{\text{op}} \rightarrow \mathbf{Cat} \dots$
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But this is perhaps overly general.

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- Should we be looking for something more specific than this?
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A morphism $\begin{bmatrix} E_1 \\ B_1 \end{bmatrix} \rightarrow \begin{bmatrix} E_2 \\ B_2 \end{bmatrix}$ in the twisted arrow category. Looks kinda lency, but should it count?

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- This works if \mathcal{B} has pullbacks.
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- If \mathcal{B} is locally cartesian closed with disjoint coproducts (e.g. a topos):

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- If \mathcal{B} is locally cartesian closed with disjoint coproducts (e.g. a topos):
- Then $\mathbf{Lens}_{\mathcal{B}/-}$ has excellent formal properties.
 - Complete, cocomplete, Cartesian closed.
 - Initial alg's and final coalg's for polynomial endofunctors.
 - Another fact'n system: $\begin{bmatrix} f^\# \\ f \end{bmatrix}$ factors as $\begin{bmatrix} E_1 \\ B_1 \end{bmatrix} \rightarrow \begin{bmatrix} f_*E_1 \\ B_2 \end{bmatrix} \rightarrow \begin{bmatrix} E_2 \\ B_2 \end{bmatrix}$

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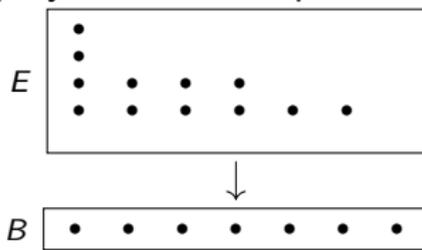
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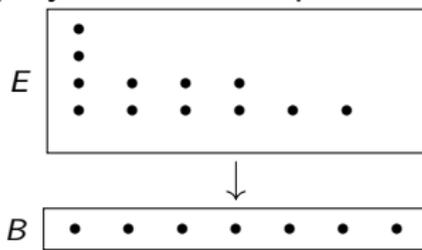
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- And they have the same morphisms too: $\mathbf{Poly}_{\mathcal{B}} \cong \mathbf{Lens}_{\mathcal{B}/-}$.

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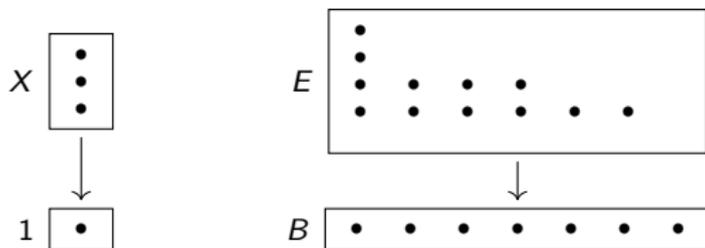
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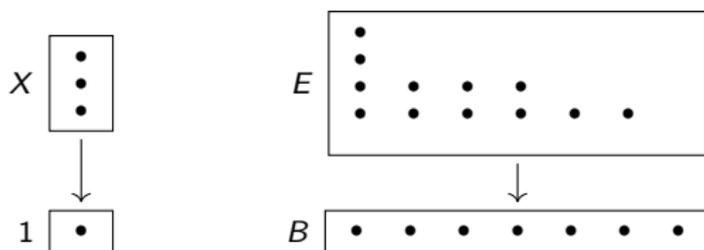
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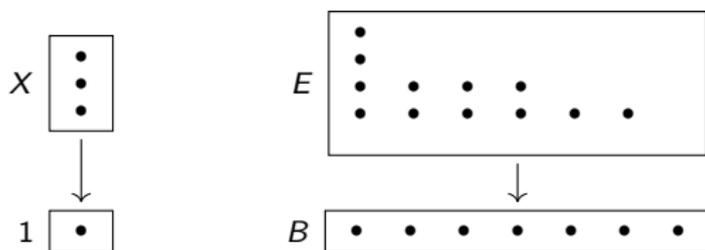
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- The functor acts on a lens $\left[\begin{smallmatrix} E \\ B \end{smallmatrix} \right] \rightarrow \left[\begin{smallmatrix} E' \\ B' \end{smallmatrix} \right]$ by composing with it.

Outline

- 1 Introduction
- 2 Some applications of lenses
- 3 Generalizing lens categories
- 4 Conclusion**

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Thanks; comments and questions welcome!